

For $r \leq m \leq 2^r - 1$

$$e_{r-1} = 1$$

$$S_1^{(1)}(m) = \begin{bmatrix} g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-2} & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & & \\ g_1 & 0 & \dots & & & 1 \\ 1 & 0 & \dots & & & 0 \end{bmatrix}^{m-r} \begin{bmatrix} e_{r-1} \\ e_{r-2} \\ \vdots \\ e_1 \\ e_0 \end{bmatrix}$$

(does this imply $e_0 = 1$ also?)

(yes; proposition is $\bar{e}_1 = \text{rev}(\bar{e}_2)$ and error pattern must have leading 1

$$S_2^{(1)}(m) = \begin{bmatrix} g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-2} & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & & \\ g_1 & 0 & \dots & & & 1 \\ 1 & 0 & \dots & & & 0 \end{bmatrix}^{m-r} \begin{bmatrix} e_0 \\ e_1 \\ \vdots \\ e_{r-1} \end{bmatrix}$$

$$S_1^{(2)}(m) = \begin{bmatrix} g_1 & 1 & 0 & \dots & 0 \\ g_2 & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & & \\ g_{r-1} & 0 & \dots & & & 1 \\ 1 & 0 & \dots & & & 0 \end{bmatrix}^{m-r} \begin{bmatrix} e_{r-1} \\ e_{r-2} \\ \vdots \\ e_1 \\ e_0 \end{bmatrix}$$

$$S_2^{(2)}(m) = \begin{bmatrix} g_1 & 1 & 0 & \dots & 0 \\ g_2 & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & & \\ g_{r-1} & 0 & \dots & & & 1 \\ 1 & 0 & \dots & & & 0 \end{bmatrix}^{m-r} \begin{bmatrix} e_0 \\ e_1 \\ \vdots \\ e_{r-2} \\ e_{r-1} \end{bmatrix}$$

Proposition: $\exists m \leq 2^r - 1$ such that

$$S_1^{(1)}(m) = S_2^{(1)}(2^r - 1) \quad \text{and} \quad S_1^{(2)}(m) = S_2^{(2)}(2^r - 1)$$

Hum... This might be the wrong proposition. But it may be equivalent. If $\exists m$ s.t. $G^m e^{(1)} = e^{(2)}$, the subsequent syndrome patterns will match since $G^{m+1} e^{(1)} = G e^{(2)}$, $G^{m+2} e^{(1)} = G^2 e^{(2)}$, ...

Then

$$G_1^{m-r} \begin{bmatrix} 1 \\ e_{r-2} \\ e_{r-3} \\ \vdots \\ e_1 \\ 1 \end{bmatrix} = G_1^{2^{r-1}-r} \begin{bmatrix} 1 \\ e_{r-1} \\ \vdots \\ e_{r-2} \\ 1 \end{bmatrix}$$

$$G_1^{m-r} \underbrace{\begin{bmatrix} 1 \\ e_{r-2} \\ e_{r-3} \\ \vdots \\ e_1 \\ 1 \end{bmatrix}}_{e^{(1)}} = G_1^{2^{r-1}-r} \underbrace{\begin{bmatrix} 1 \\ e_1 \\ e_2 \\ \vdots \\ e_{r-2} \\ 1 \end{bmatrix}}_{e^{(2)}}$$

$$\Rightarrow G_1^m e^{(1)} = G_1^{2^r-1} e^{(2)}$$

Is there any special property
about $G_1^{2^r-1}$?

There should be because code
is cyclic

Look at example

$$g(x) = x^3 + x + 1 \Rightarrow g_1 = 1 \quad g_2 = 0 \quad r = 3$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}^2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$G^3 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$G^4 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$G^5 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$G^6 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$G^7 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$$

$$\therefore \underline{\underline{G^{2^r-1} = I}}$$

$$\therefore \boxed{G_1^m e^{(1)} = e^{(2)}} \quad \leftarrow \text{image condition}$$

Now let $f(x) = x^3 + x^2 + 1$

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}^2 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix}$$

$$G^3 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$G^4 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$G^5 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$G^6 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$G^7 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \checkmark$$

Since G is $r \times r$, it's easy enough to use the computer to verify all the bit-reversed cases (though it may take awhile!). It's tougher to show that the condition is not met for $e^{(1)} \neq \text{rev}(e^{(1)})$. Or is it? The argument is a symmetry argument which involves both G_1 and G_2 .

1 0 1
1 0 0
0 1 0

Since

$$e^{(1)} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ e_{r-2} \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ e_{r-3} \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \dots + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

$$e^{(2)} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ e_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ e_2 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \dots + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

does it do any good to expand the "key" equation?

Since $e^{(2)} = \text{rev}(e^{(1)})$ rev = row reversal operation

$$\text{rev}[G_1^m e^{(1)}] = e^{(1)}$$

Let $h_{ij} = i, j^{\text{th}}$ entry of G_1^m

Then

$$G_1^m e^{(1)} = \begin{bmatrix} h_{0,0} & h_{0,1} & \dots & h_{0,r-1} \\ h_{1,0} & h_{1,1} & \dots & h_{1,r-1} \\ \vdots & \vdots & \ddots & \vdots \\ h_{r-1,0} & h_{r-1,1} & \dots & h_{r-1,r-1} \end{bmatrix} \begin{bmatrix} 1 \\ e_{r-2} \\ \vdots \\ e_1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \sum_{i=0}^{r-1} h_{0,i} e_i^{(1)} \\ \sum_{i=0}^{r-1} h_{1,i} e_i^{(1)} \\ \vdots \\ \sum_{i=0}^{r-1} h_{r-1,i} e_i^{(1)} \end{bmatrix}$$

$$\therefore \text{rev}[G_1^m e^{(1)}] = \begin{bmatrix} \sum_{i=0}^{r-1} h_{r-1,i} e_i^{(1)} \\ \vdots \\ \sum_{i=0}^{r-1} h_{0,i} e_i^{(1)} \end{bmatrix} = \text{rev}(G_1^m) e^{(1)}$$

$$\Rightarrow \text{rev}(G_1^m) e^{(1)} = e^{(1)}$$

$$\Rightarrow \text{rev}(G_1^m) = I \Rightarrow m = 2^r - 1 \quad \text{for general case}$$

• However, this must not be the only solution. This is the trivial case.

General condition requires

$$\sum_{i=0}^{r-1} h_{j,i} e_i^{(1)} = e_j^{(1)}$$

This is equivalent to

$$\sum_{i=0}^{r-1} h_{j,i} e_i^{(1)} = e_j^{(1)}$$

$$h_{j,i} \neq 0$$

but this isn't getting me much closer!

Key equation

$$G_1^m e^{(1)} = e^{(2)} \quad \text{and} \quad G_2^m e^{(1)} = e^{(2)}$$

$$\Rightarrow G_1^m e^{(1)} = G_2^m e^{(1)}$$

$$\Rightarrow (G_1^m - G_2^m) e^{(1)} = 0$$

$$\Rightarrow G_1^m - G_2^m = 0 \quad \text{as one case. (Not necessarily the only case)}$$

$$\Rightarrow G_1^m = G_2^m$$

$$\Rightarrow \begin{bmatrix} g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-2} & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ g_1 & 0 & \dots & \dots & 1 \\ 1 & 0 & \dots & \dots & 0 \end{bmatrix}^m = \begin{bmatrix} g_1 & 1 & 0 & \dots & 0 \\ g_2 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ g_{r-1} & 0 & \dots & \dots & 1 \\ 1 & 0 & \dots & \dots & 0 \end{bmatrix}^m$$

(This one's independent of $e^{(1)}$ and $e^{(2)}$ so it's not even "the" vital case unless no solution exists for it)

$$G_1 = \begin{bmatrix} g_{r-1}^2 + g_{r-2} & g_{r-1} & g_{r-2} & \dots & g_1 \\ g_{r-1}g_{r-2} + g_{r-3} & g_{r-2} & g_{r-3} & \dots & g_2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ g_1 & 0 & \dots & \dots & 1 \\ 1 & 0 & \dots & \dots & 0 \end{bmatrix}$$

$$G_1^2 = \begin{bmatrix} g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-2} & 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & & & \\ g_1 & 0 & 0 & \dots & 1 \\ 1 & 0 & 0 & \dots & 0 \end{bmatrix} \begin{bmatrix} g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-2} & 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & & & \\ g_1 & 0 & \dots & \dots & 1 \\ 1 & 0 & \dots & \dots & 0 \end{bmatrix}$$

$$= \begin{bmatrix} g_{r-1} + g_{r-2} & g_{r-1} & 1 & 0 & \dots & 0 \\ g_{r-1}g_{r-2} + g_{r-3} & g_{r-2} & 0 & 1 & 0 & \dots & 0 \\ g_{r-1}g_{r-3} + g_{r-4} & g_{r-3} & 0 & 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & & & & & \\ g_{r-1} & 1 & 0 & \dots & \dots & \dots & 0 \end{bmatrix}$$

well, this gets
me nowhere fast!

$$G_1 = \begin{bmatrix} g_{r-1} & 1 & & & \\ g_{r-2} & & & & \\ \vdots & & & & \\ g_0 & & & & \\ & & I & & \\ & & & & & 0 \end{bmatrix}$$

$$G_2 = \begin{bmatrix} g_0 & 1 & & & \\ g_1 & & & & \\ \vdots & & & & \\ g_{r-1} & & & & \\ & & I & & \\ & & & & & 0 \end{bmatrix}$$

$$G_1^T = \begin{bmatrix} g_{r-1} & g_{r-2} & \dots & g_0 \\ & & & \\ & I & & \\ & & & 0 \end{bmatrix}$$

hmm ... is there any way to diagonalize G_1 and G_2 ?

$$G_1^m e^{(1)} = e^{(2)} = G_2^m e^{(1)}$$

$$e^{(2)} e^{(2)T} = \begin{bmatrix} 1 \\ e_1 \\ e_2 \\ \vdots \\ e_{r-2} \\ 1 \end{bmatrix} [1 \ e_1 \ e_2 \ \dots \ e_{r-2} \ 1] = \begin{bmatrix} 1 & e_1 & e_2 & \dots & e_{r-2} & 1 \\ e_1 & e_1^2 & e_1 e_2 & \dots & e_1 e_{r-2} & e_1 \\ e_2 & e_2 e_1 & e_2^2 & \dots & e_2 e_{r-2} & e_2 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ e_{r-2} & e_{r-2} e_1 & \dots & e_{r-2}^2 & e_{r-2} & e_{r-2} \\ 1 & e_1 & e_2 & \dots & e_{r-2} & 1 \end{bmatrix}$$

rank $\leq r-1$

$$e^{(1)} e^{(2)T} = \begin{bmatrix} 1 \\ e_{r-2} \\ \vdots \\ e_2 \\ e_1 \\ 1 \end{bmatrix} [1 \ e_1 \ e_2 \ \dots \ e_{r-2} \ 1] = \begin{bmatrix} 1 & e_1 & e_2 & \dots & e_{r-2} & 1 \\ e_{r-2} & e_{r-2} e_1 & \dots & e_{r-2}^2 & e_{r-2} & e_{r-2} \\ \vdots & \vdots & & & \vdots & \vdots \\ e_1 & e_1^2 & e_1 e_2 & \dots & e_1 e_{r-2} & e_1 \\ 1 & e_1 & e_2 & \dots & e_{r-2} & 1 \end{bmatrix} = \text{rev} \left(e^{(2)} e^{(2)T} \right)$$